## Fundamentals of Road Construction

## Lecturer :

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## Lecture 3

## The subject of the lecture: Horizontal alignment

Uczelnia zintegrowana na przyszłość POWR.03.05.00-00-Z041/17

## Coordinates of vertex points of horizontal alignment of the design road:



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| Point | Coordinates $[\mathrm{m}]$ |  |
| :---: | ---: | ---: |
|  | X | Y |
| A | 90,00 | 1400,00 |
| $\mathrm{~W}_{1}$ | 655,05 | 1145,05 |
| $\mathrm{~W}_{2}$ | 765,65 | 704,15 |
| $\mathrm{~W}_{3}$ | 1356,55 | 283,45 |
| $\mathrm{~W}_{4}$ | 2300,07 | 268,08 |
| B | 2485,00 | 50,00 |



## Distance (length) between vertex points:

$$
\begin{aligned}
& \overline{A W_{1}}=\sqrt{\left(X_{W 1}-X_{A}\right)^{2}+\left(Y_{W 1}-Y_{A}\right)^{2}} \\
& \overline{\overline{A W_{1}}=\sqrt{(655,05 m-90,00 m)^{2}+(1145,05 m-1400,00 m)^{2}}}=619,90 \mathrm{~m}
\end{aligned}
$$

| Section | Distance [m] |
| :---: | :---: |
| $\overline{A W_{1}}$ | 619,90 |
| $\overline{W_{1} W_{2}}$ | 454,56 |
| $\overline{W_{2} W_{3}}$ | 725,36 |
| $\overline{W_{3} W_{4}}$ | 943,65 |
| $\overline{W_{4} B}$ | 285,94 |
| $\Sigma$ | 3029,41 |

## Deflection angle of horizontal alignment of the design road:

CIRCULAR HORIZONTAL CURVES


| $\mathrm{BC}=$ Beginning of Curve | $\mathrm{EC}=$ End of Curve |
| :---: | :---: |
| $\mathrm{PC}=$ Point of Curve | $\mathrm{PT}=$ Point of Tangent |
| $\mathrm{TC}=$ Tangent to Curve | $\mathrm{CT}=$ Curve to Tangent |

Source: https://www.cpp.edu/~hturner/ce220/circular_curves.pdf


$$
\begin{gathered}
\cos \beta_{1}=\frac{{\overline{A W_{1}}}^{2}+{\overline{W_{1} W_{2}}}^{2}-{\overline{A W_{2}}}^{2}}{2 \cdot \overline{A W}_{1} \cdot \overline{W W}_{1} W_{2}} \\
\gamma_{1}=180^{\circ}-\beta_{1} \\
\cos \beta_{1}=\frac{(619,90)^{2}+(454,56)^{2}-(969,90)^{2}}{2 \cdot 619,90 \cdot 454,56}=-0,620696 \\
\beta_{1}=128,3669^{\circ} \\
\gamma_{1}=180^{\circ}-128,3669^{\circ}=51,6331^{\circ}
\end{gathered}
$$

|  | Deflection angle $\gamma$ |  |  |
| :---: | :---: | :---: | :---: |
|  | $\left[{ }^{\circ}\right]$ |  | $[\mathrm{rad}]$ |
| $\gamma_{1}$ | $51^{\circ} 37^{\prime} 59^{\prime \prime}$ | 51,6331 | 0,901167 |
| $\gamma_{2}$ | $40^{\circ} 28^{\prime} 06^{\prime \prime}$ | 40,4684 | 0,706306 |
| $\gamma_{3}$ | $34^{\circ} 30^{\prime} 59^{\prime \prime}$ | 34,5163 | 0,602422 |
| $\gamma_{4}$ | $48^{\circ} 46^{\prime} 09^{\prime \prime}$ | 48,7691 | 0,851181 |

## Tortuosity of section of the design road:

$K=\frac{\sum_{i=1}^{n}\left|\gamma_{n}\right|}{L}[\% / \mathrm{km}]$, where:
K - tortuosity of the section of the design road [ $\% / \mathrm{km}$ ]
$\Sigma \gamma_{\mathrm{n}}$ - sum of the absolute deflection angles of horizontal alignment [ ${ }^{\circ}$ ]
L - distance between vertices [km]
n - number of vertices [-]
$K=\frac{51,6331^{\circ}+40,4684^{\circ}+34,5163^{\circ}+48,7691^{\circ}}{3,03}=\frac{175,3867^{\circ}}{3,03}$

## Checking the requirements for the assumed radius of horizontal curves

The adoption of horizontal curve radius based on regulation of the Minister of Transport and Maritime Economy (consolidated text, Journal of Laws of 2016, item 124, as amended) - in short JoL16.
a) roll-over stability condition
$R_{\text {min }}=\frac{v^{2}}{g \cdot\left(\frac{b}{2 h} \pm i_{0}\right)},[\mathrm{m}]$ where:
v - speed $[\mathrm{m} / \mathrm{s}$ ]
$v=\left\{\begin{array}{l}v_{p}-\text { road of the class } \mathrm{Z} \text { and lower (desgin speed) } \\ v_{m}-\text { road of the class } \mathrm{G} \text { and upper (reliable speed) }\end{array}\right.$
g - acceleration due to gravity $\mathrm{g} \approx 9,81 \mathrm{~m} / \mathrm{s}^{2}$
b- wheelbase vehicle (passenger car $1.5-1.8 \mathrm{~m}$, lorry $2.0-2.4 \mathrm{~m}$ )
h - height of the center of gravity of the vehicle (passenger car 0.9-1.2 m, lorry $1.5-1.6 \mathrm{~m}$ )
$i_{0}$ - the transverse slope of the road on the curve $[-]$

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$$
R_{\min }= \begin{cases}\frac{v_{p}{ }^{2}}{g \cdot\left(\frac{b}{2 h}-i_{0}\right)}[m] & \text { - slope of the trafficway in the shape of a canopy } \\ \frac{v_{p}{ }^{2}}{g \cdot\left(\frac{b}{2 h}+i_{0}\right)}[m] & \text { - one-side slope of the trafficway }\end{cases}
$$

$$
R_{\min }^{(2)}=\frac{16,67^{2}}{9,81 \cdot\left(\frac{1,50}{2 \cdot 1,20}+0,04\right)}=42,60 \mathrm{~m}
$$

|  | $\mathbf{i}_{\mathbf{o}}[\%]$ | $\mathbf{R}_{\text {min }}{ }^{(2)}$ |  |
| :---: | :---: | :---: | :---: |
|  |  | $\mathbf{+ i}_{\mathbf{o}}$ | $\mathbf{i}_{\mathbf{o}}$ |
| W1 | 4,0 | $\mathbf{4 2 , 6 0}$ | - |
| W2 | 3,5 | $\mathbf{4 2 , 9 2}$ | - |
| W3 | 3,0 | $\mathbf{4 3 , 2 5}$ | - |
| W4 | 5,0 | $\mathbf{4 1 , 9 7}$ | - |

b) slip stability condition

$$
R_{\min }=\frac{v^{2}}{g \cdot\left(\varphi_{R} \pm i_{0}\right)}[\mathrm{m}] \text {, where: }
$$

v - speed [ $\mathrm{m} / \mathrm{s}$ ]
$v=\left\{\begin{array}{l}v_{p}-\text { road of the class } \mathrm{Z} \text { and lower (desgin speed) } \\ v_{m}-\text { road of the class } \mathrm{G} \text { and upper (reliable speed) }\end{array}\right.$
g - acceleration due to gravity $\mathrm{g} \approx 9,81 \mathrm{~m} / \mathrm{s}^{2}$
$\varphi_{R}$ - coefficient of transverse adhesion of the tire to the road
$i_{0}$ - the transverse slope of the road on the curve [-]

$$
R_{\min }= \begin{cases}\frac{v_{p}{ }^{2}}{g \cdot\left(\varphi_{R}-i_{0}\right)}[m] & \text { - slope of the trafficway in the shape of a canopy } \\ \frac{v_{p}{ }^{2}}{g \cdot\left(\varphi_{R}+i_{0}\right)}[m] & \text { - one-side slope of the trafficway }\end{cases}
$$

$$
\varphi_{R}=0,2[-]
$$

wet asphalt surface

$$
R_{\min }^{(3)}=\frac{16,67^{2}}{9,81 \cdot(0,20+0,04)}=118,03 \mathrm{~m}
$$

|  | $i_{0}[\%]$ | $\mathbf{R}_{\text {min }}{ }^{(3)}[\mathbf{m}]$ |  |
| :---: | :---: | :---: | :---: |
|  |  | $\mathbf{i}_{\mathbf{o}}$ | $-\mathbf{i}_{\mathbf{o}}$ |
| W1 | 4,0 | $\mathbf{1 1 8 , 0 3}$ | - |
| W2 | 3,5 | $\mathbf{1 2 0 , 5 4}$ | - |
| W3 | 3,0 | $\mathbf{1 2 3 , 1 6}$ | - |
| W4 | 5,0 | $\mathbf{1 1 3 , 3 1}$ | - |

## c) driving comfort condition

$\left[R_{\min }=\frac{v^{2}}{g \cdot\left(\mu \pm i_{0}\right)} \quad[\mathrm{m}]\right.$, where:
v - speed [ $\mathrm{m} / \mathrm{s}$ ]
$v=\left\{\begin{array}{l}v_{P}-\text { road of the class } \mathrm{Z} \text { and lower (desgin speed) } \\ v_{m}-\text { road of the class } \mathrm{G} \text { and upper (reliable speed) }\end{array}\right.$
$g$ - acceleration due to gravity $g \approx 9,81 \mathrm{~m} / \mathrm{s}^{2}$
$\mu$ - transverse acceleration factor [-]
$i_{0}$ - the transverse slope of the road on the curve [-]
$R_{\min }= \begin{cases}\frac{v_{p}{ }^{2}}{g \cdot\left(\mu-i_{0}\right)}[m] & \text { - slope of the trafficway in the shape of a canopy } \\ \frac{v_{p}{ }^{2}}{g \cdot\left(\mu+i_{0}\right)}[m] & \text { - one-side slope of the trafficway }\end{cases}$


It stands out due to the driving comfort:

- $\mu=0,02-$ a passenger who does not observe the road, will not distinguish driving between section of straight or curved; the driver feels no tension
$-\mu=0,06-$ a passenger has a poor feel of driving along the curvilinear section; the driver feels small tension
- $\mu=0,10-$ a passenger feels the driving along the curvilinear section, but does not feel discomfort: the driver clearly feels the tension
$-\mu=0,17-$ driving along a curvilinear section is inconvenient for everyone
adopted $\boldsymbol{\mu}=\mathbf{0 , 1 0}[-], \quad$ possibly $\mu=0,12[-]$

$$
R_{\min }^{(4)}=\frac{16,67^{2}}{9,81 \cdot(0,10+0,04)}=202,34 \mathrm{~m}
$$

|  | $\mathbf{i}_{\mathbf{o}}[\%]$ | $\mathbf{R}_{\text {min }^{(4)}}$ |  |
| :---: | :---: | :---: | :---: |
|  |  | $+\mathbf{i}_{\mathbf{o}}$ | $-\mathbf{i}_{\mathbf{o}}$ |
| W1 | 4,0 | $\mathbf{2 0 2 , 3 4}$ | - |
| W2 | 3,5 | $\mathbf{2 0 9 , 8 3}$ | - |
| W3 | 3,0 | $\mathbf{2 1 7 , 9 0}$ | - |
| W4 | 5,0 | $\mathbf{1 8 8 , 8 5}$ | - |

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## JUXTAPOSITION $\mathrm{R}_{\text {min }}$

|  | $\underset{\mathbf{R o L}^{(\mathbf{1})}}{{ }^{2}}$ | $\begin{aligned} & \mathbf{R}_{\min }{ }^{(2)} \\ & \text { roll-over } \end{aligned}$ | $\underset{\text { slip }}{\mathbf{R}_{\text {min }}{ }^{(3)}}$ | $\begin{aligned} & \mathbf{R}_{\text {min }}{ }^{(4)} \\ & \text { comfort } \end{aligned}$ | $\mathrm{i}_{0}$ [\%] | Adopted R [m] |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| W1 | 250 | 42,60 | 118,03 | 202,34 | 4,0 | 250 |
| W2 | 320 | 42,92 | 120,54 | 209,83 | 3,5 | 320 |
| W3 | 380 | 43,25 | 123,16 | 217,90 | 3,0 | 380 |
| W4 | 200 | 41,97 | 113,31 | 188,85 | 5,0 | 200 |

## Calculation of basic elements of a horizontal curve



Signs:
PŁK - $B C$ - begin of curve
$K Ł K-E C$ - end of curve
Z-E - external
T - tangent

## Curve 1

$$
\gamma_{1}=51,6331^{\circ} \quad R_{1}=250 \mathrm{~m}
$$

- calculating the tangent of a curve

$$
T_{1}=R_{1} \cdot \operatorname{tg} \frac{\gamma_{1}}{2}=250 \cdot \operatorname{tg} \frac{51,6331}{2}=120,94 \mathrm{~m}
$$

- calculating the external of a curve

$$
Z_{1}=\frac{R_{1}}{\cos \frac{\gamma_{1}}{2}}-R_{1}=250 \cdot\left(\frac{1}{\cos \frac{51,6331^{\circ}}{2}}-1\right)=27,72 m
$$

- curve length calculation

$$
D_{1}=R_{1} \cdot \frac{\pi}{180} \cdot \gamma_{1}=250 \cdot \frac{\pi}{180} \cdot 51,6331^{\circ}=225,29 \mathrm{~m}
$$

- calculation of the widening on a curve

$$
\frac{40}{R}=\frac{40}{250}=0,16 \mathrm{~m}
$$

The widening is used when its value is greater than or equal to 0.2 m


|  | $\mathrm{R}[\mathrm{m}]$ | $\gamma\left[{ }^{\circ}\right]$ | $\mathrm{T}[\mathrm{m}]$ | $\mathrm{Z}[\mathrm{m}]$ | $\mathrm{D}[\mathrm{m}]$ | $\frac{40}{R}$ | $\mathrm{p}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Curve 1 | 250 | 51,6331 | 120,94 | 27,72 | 225,29 | 0,16 | - |
| Curve 2 | 320 | 40,4684 | 117,95 | 21,05 | 226,02 | 0,13 | - |
| Curve 3 | 380 | 34,5163 | 118,05 | 17,91 | 228,92 | 0,11 | - |
| Curve 4 | 200 | 48,7691 | 90,66 | 19,59 | 170,24 | 0,20 | 0,20 |

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## Determination of the clothoid a-parameter



Source: https://pwayblog.com/2016/07/03/the-clothoid/


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The road ramp


Source: https://docplayer.pl/docs-images/64/51106521/images/11-1.jpg


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## Determination of the clothoid a-parameter

a) dynamics condition

$$
a_{\min }=\sqrt{\frac{v^{3}}{k}}[m], \text { where: }
$$

a - clothoid a-parameter [m]
v - speed [m/s]
$v=v_{p} \quad$ for all road classes $\Rightarrow v=v_{P}=60 \frac{\mathrm{~km}}{\mathrm{~h}} \Rightarrow v=16,67 \frac{\mathrm{~m}}{\mathrm{~s}}$
$k$ - permissible increase centripetal acceleration $\quad \Rightarrow V_{P}=60 \frac{\mathrm{~km}}{\mathrm{~h}} \Rightarrow k=0,7 \frac{\mathrm{~m}}{\mathrm{~s}^{3}}$

$$
a_{\min }=\sqrt{\frac{16,67^{3}}{0,7}}=81,35 m
$$

b) aesthetics condition

$$
\begin{gathered}
a_{\min }=\frac{1}{3} R[m] \\
a \quad=R[m], \text { where: }
\end{gathered}
$$

R- radius of the horizontal curve [ m ]

$$
\begin{gathered}
a_{1 \min }=\frac{1}{3} \cdot 200=66,67 \mathrm{~m} \\
a_{1 \text { max }}=200 \mathrm{~m}
\end{gathered}
$$

|  | $\mathrm{R}[\mathrm{m}]$ | $\mathbf{a}_{\text {min }}[\mathrm{m}]$ | $\mathbf{a}_{\max }[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: |
| curve 1 | 250 | $\mathbf{8 3 , 3 3}$ | $\mathbf{2 5 0}$ |
| curve 2 | 320 | $\mathbf{1 0 6 , 6 7}$ | $\mathbf{3 2 0}$ |
| curve 3 | 380 | $\mathbf{1 2 6 , 6 7}$ | $\mathbf{3 8 0}$ |
| curve 4 | 200 | $\mathbf{6 6 , 6 7}$ | $\mathbf{2 0 0}$ |

## c) construction of a road ramp condition

$a_{\min }=\sqrt{\frac{R \cdot B}{2} \cdot \frac{i_{n}+i_{o}}{i_{d \max }}}[\mathrm{~m}]$, where:
$R$ - radius of the horizontal curve [m]
$B$ - roadway width [m]; traffic line width outside the built-up area for a Z-class road
is $2.75-3.00 \mathrm{~m}$; adopted $6,00 \mathrm{~m}$
$i_{o}$ - the transverse slope of the roadway on a curvilinear section [-]
$i_{n}$ - the transverse slope of the roadway on a straight section
$i_{d}$ - additional slope of the roadway on the road ramp [-]
$i_{d \text { min }} \leq i_{d} \leq i_{d \text { max }}$
$i_{d \text { min }}=0,1 \cdot \frac{B}{2}=0,1 \cdot \frac{6,00}{2}=0,3 \%$
$i_{d \max }=1,6 \% \quad$ for design speed $\quad v_{P}=60 \frac{\mathrm{~km}}{\mathrm{~h}}$
$0,003 \leq i_{d} \leq 0,016 \quad$ adopted $\quad i_{d}=0,016$

$$
a_{1 \min }=\sqrt{\frac{250 \cdot 6,00}{2} \cdot \frac{0,02+0,04}{0,016}}=53,03 \mathrm{~m}
$$

|  | $\mathrm{R}[\mathrm{m}]$ | $\mathrm{B}[\mathrm{m}]$ | $\mathrm{i}_{\mathrm{n}}[\%]$ | $\mathrm{i}_{\mathrm{o}}[\%]$ | $\mathrm{i}_{\mathrm{d}}[\%]$ | $\mathrm{a}_{\text {min }}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| curve 1 | 250 | 6,00 | 2,0 | 4,0 | 1,6 | $\mathbf{5 3 , 0 3}$ |
| curve 2 | 320 | 6,00 | 2,0 | 3,5 | 1,6 | $\mathbf{5 7 , 4 5}$ |
| curve 3 | 380 | 6,00 | 2,0 | 3,0 | 1,6 | $\mathbf{5 9 , 6 9}$ |
| curve 4 | 200 | 6,40 | 2,0 | 5,0 | 1,6 | $\mathbf{5 2 , 9 2}$ |

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d) widening of the roadway condition
calculated for the horizontal curves which have widening
$a_{\min }=1,86 \cdot \sqrt[4]{R^{3} \cdot p_{c}} \quad[\mathrm{~m}]$, where:
R - radius of the horizontal curve [ m ]
$\mathrm{p}_{\mathrm{c}}$ - complete widening of the roadway on the curve [m]
$a_{4 \text { min }}=1,86 \cdot \sqrt[4]{200^{3} \cdot 0,4}=78,67 \mathrm{~m}$
e) geometric condition
$a_{\max }=R \cdot \sqrt{\gamma}[\mathrm{~m}]$, where:

R - radius of the horizontal curve Iml
$\gamma$-deflection angle of the horizontal curve [rad]
$a_{1 \max }=250 \cdot \sqrt{0,901167}=237,32 \mathrm{~m}$

|  | $\mathbf{R}[\mathrm{m}]$ | $\gamma[\mathrm{rad}]$ | $\mathbf{a}_{\max }[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: |
| curve 1 | 250 | 0,901167 | $\mathbf{2 3 7 , 3 2}$ |
| curve 2 | 320 | 0,706306 | $\mathbf{2 6 8 , 9 3}$ |
| curve 3 | 380 | 0,602422 | $\mathbf{2 9 4 , 9 4}$ |
| curve 4 | 200 | 0,851181 | $\mathbf{1 8 4 , 5 2}$ |

## f) horizontal curve offset condition

recommended condition
for $\quad H_{\text {min }}=0,50 m \Rightarrow a_{\text {min }}=1,863 \cdot R^{\frac{3}{4}}[\mathrm{~m}]$,
for $H_{\text {max }}=2,50 \mathrm{~m} \Rightarrow a_{\text {max }}=2,783 \cdot R^{\frac{3}{4}} \quad[\mathrm{~m}]$, where:
H - horizntal curve offset [ m ]

$$
\begin{aligned}
& a_{1 \min }=1,863 \cdot 250^{\frac{3}{4}}=117,00 \mathrm{~m} \\
& a_{1 \max }=2,783 \cdot 250^{\frac{3}{4}}=174,97 \mathrm{~m}
\end{aligned}
$$

|  | $\mathrm{R}[\mathrm{m}]$ | $\mathbf{a}_{\min }[\mathrm{m}]$ | $\mathbf{a}_{\text {max }}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: |
| curve 1 | 250 | $\mathbf{1 1 7 , 0 0}$ | $\mathbf{1 7 4 , 9 7}$ |
| curve 2 | 320 | $\mathbf{1 4 0 , 8 0}$ | $\mathbf{2 1 0 , 5 6}$ |
| curve 3 | 380 | $\mathbf{1 6 0 , 1 7}$ | $\mathbf{2 3 9 , 5 3}$ |
| curve 4 | 200 | $\mathbf{9 8 , 9 7}$ | $\mathbf{1 4 8 , 0 1}$ |

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g) proportionality condition
recommended condition
for $\mathrm{L}: \mathrm{\ell}: \mathrm{L}=1: 4: 1 \Rightarrow a_{\min }=R \cdot \sqrt{\frac{\gamma}{5}}[\mathrm{~m}]$,
for $\mathrm{L}: \mathrm{E}: \mathrm{L}=1: 1: 1 \Rightarrow a_{\max }=R \cdot \sqrt{\frac{\gamma}{2}} \quad[\mathrm{~m}]$, gdzie:
R- radius of the horizontal curve [ m ]
$\gamma$ - deflection angle [rad]

$$
\begin{aligned}
& a_{1 \min }=250 \cdot \sqrt{\frac{0,901167}{5}}=106,13 \mathrm{~m} \\
& a_{1 \max }=250 \cdot \sqrt{\frac{0,901167}{2}}=167,81 \mathrm{~m}
\end{aligned}
$$

|  | $\mathrm{R}[\mathrm{m}]$ | $\gamma[\mathrm{rad}]$ | $\mathbf{a}_{\min }[\mathrm{m}]$ | $\mathbf{a}_{\max }[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: | :---: |
| curve 1 | 250 | 0,901167 | $\mathbf{1 0 6 , 1 3}$ | $\mathbf{1 6 7 , 8 1}$ |
| curve 2 | 320 | 0,706306 | $\mathbf{1 2 0 , 2 7}$ | $\mathbf{1 9 0 , 1 7}$ |
| curve 3 | 380 | 0,602422 | $\mathbf{1 3 1 , 9 0}$ | $\mathbf{2 0 8 , 5 5}$ |
| curve 4 | 200 | 0,851181 | $\mathbf{8 2 , 5 2}$ | $\mathbf{1 3 0 , 4 7}$ |

Signs:
$\mathrm{L}-\mathrm{Cl}$ - the length of the clothoid $t-\mathrm{Cu}$ - the length of the curve

JUXTAPOSITION OF A-PARAMETER VALUES

|  | $\mathbf{R}$ [m] | $\begin{aligned} & \mathbf{a}_{\text {min }} \quad[\mathrm{m}] \\ & \text { dyn } \end{aligned}$ | $\begin{aligned} & \mathbf{a}_{\text {min }}[\mathrm{m}] \\ & \text { asth } \end{aligned}$ | $\begin{aligned} & \mathbf{a}_{\text {min }}[\mathrm{m}] \\ & \text { const } \end{aligned}$ | $\begin{aligned} & \mathbf{a}_{\min }[\mathrm{m}] \\ & \text { widening } \end{aligned}$ | $\begin{aligned} & \mathbf{a}_{\min }[\mathrm{m}] \\ & \text { offset } \end{aligned}$ | $\begin{aligned} & \mathbf{a}_{\text {min }}[\mathrm{m}] \\ & \text { prop } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| curve 1 | 250 | 81,33 | 83,33 | 53,03 | - | 117,00 | 106,13 |
| curve 2 | 320 | 81,33 | 106,67 | 57,45 | - | 140,80 | 120,27 |
| curve 3 | 380 | 81,33 | 126,67 | 59,69 | - | 160,17 | 131,90 |
| curve 4 | 200 | 81,33 | 66,67 | 52,92 | 78,67 | 98,97 | 82,52 |


|  | $\mathbf{R}[\mathrm{m}]$ | $\mathbf{a}_{\max }[\mathrm{m}]$ <br> asth | $\mathbf{a}_{\max }$ geom <br> geo | $\mathbf{a}_{\text {max }}$ offset | $\mathbf{a}_{\text {max }}$ prop |
| :---: | :---: | :---: | :---: | :---: | :---: |
| curve 1 | 250 | 250 | 237,32 | 174,97 | 167,81 |
| curve 2 | 320 | 320 | 268,93 | 210,56 | 190,17 |
| curve 3 | 380 | 380 | 294,94 | 239,53 | 208,55 |
| curve 4 | 200 | 200 | 184,52 | 148,01 | 130,47 |

ADOPTION OF A-PARAMETER VALUE

$$
a_{\min }^{(\max )} \leq a \leq a_{\max }^{(\min )}
$$

|  | $\mathbf{R}[\mathrm{m}]$ | $\mathbf{a}_{\text {min }}{ }^{(\max )}[\mathrm{m}]$ | $\mathbf{a}_{\text {max }}{ }^{(\text {min })}[\mathrm{m}]$ | $\mathbf{a}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: | :---: |
| curve 1 | 250 | 117,00 | 167,81 | $\mathbf{1 3 6 , 9 3}$ |
| curve 2 | 320 | 140,80 | 190,17 | $\mathbf{1 5 4 , 9 2}$ |
| curve 3 | 380 | 160,17 | 208,55 | $\mathbf{1 6 9 , 9 4}$ |
| curve 4 | 200 | 98,97 | 130,47 | $\mathbf{1 0 9 , 5 5}$ |

Uczelnia zintegrowana na przyszłość

## Determination of characteristic values of a colloidal transition curve



Source: https://pwayblog.com/2016/07/03/the-clothoid/


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a) clothoid length
$L=\frac{a^{2}}{R}[\mathrm{~m}]$, where:
L- length of the clothoid [ m ]
a- clothoid a-parameter [m]
R- radius of horizntal curve [m]

$$
L=\frac{136,93^{2}}{250}=75,00 \mathrm{~m}
$$

|  | $\mathrm{R}[\mathrm{m}]$ | $\mathrm{a}[\mathrm{m}]$ | $\mathrm{L}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: |
| curve 1 | 250 | 136,93 | $\mathbf{7 5 , 0 0}$ |
| curve 2 | 320 | 154,92 | $\mathbf{7 5 , 0 0}$ |
| curve 3 | 380 | 169,94 | $\mathbf{7 6 , 0 0}$ |
| curve 4 | 200 | 109,55 | $\mathbf{6 0 , 0 0}$ |

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b) tangent angle at the end of the transition curve

$$
\begin{gathered}
\tau=\frac{L}{2 \cdot R} \\
\tau_{\min }=3^{\circ} \leq \tau \leq \tau_{\max }=30^{\circ}, \text { where: }
\end{gathered}
$$

$\tau$ - tangent angle at the end of the transition curve [rad]
L - length of the clothoid [m]
R - radius of the horizontal curve [ m ]

$$
\tau=\frac{75,00}{2 \cdot 250}=0,150000 \quad \mathrm{rad}
$$

|  | $\mathbf{R}[\mathrm{m}]$ | $\mathbf{L}[\mathrm{m}]$ | $\tau[\mathrm{rad}]$ | $\tau\left[{ }^{\circ}\right]$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| curve 1 | 250 | 75,00 | 0,150000 | $8^{\circ} 35^{\prime} 40^{\prime \prime}$ | $\mathbf{8 , 5 9 4 4}$ |
| curve 2 | 320 | 75,00 | 0,117188 | $6^{\circ} 42^{\prime} 52^{\prime \prime}$ | $\mathbf{6 , 7 1 4 3}$ |
| curve 3 | 380 | 76,00 | 0,100000 | $5^{\circ} 43^{\prime} 46^{\prime \prime}$ | $\mathbf{5 , 7 2 9 6}$ |
| curve 4 | 200 | 60,00 | 0,150000 | $8^{\circ} 35^{\prime} 40^{\prime \prime}$ | $\mathbf{8 , 5 9 4 4}$ |

For all transition curve the condition $\tau_{\min }=3^{\circ} \leq \tau \leq \tau_{\max }=30^{\circ}$ is fulfilled
c) coordinates of the end of the transition curve

$$
X=L-\frac{L^{5}}{40 a^{4}}+\frac{L^{9}}{3456 a^{8}}-(\ldots)[m] \quad Y=\frac{L^{3}}{6 a^{2}}-\frac{L^{7}}{336 a^{6}}+\frac{L^{11}}{42240 a^{10}}-(\ldots)[m], \quad \text { where: }
$$

X- coordinates of the end of the transition curve [ m ]
Y- coordinates of the end of the transition curve [ m ]

$$
X=75,00-\frac{75,00^{5}}{40 \cdot 136,93^{4}}+(\ldots)=74,83 m
$$

$$
Y=\frac{75,00^{3}}{6 \cdot 136,93^{2}}-\frac{75,00^{7}}{336 \cdot 136,93^{6}}+(\ldots)=3,74 m
$$

|  | $\mathbf{L}[\mathrm{m}]$ | $\mathbf{a}[\mathrm{m}]$ | $\mathbf{X}[\mathrm{m}]$ | $\mathbf{Y}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: | :---: |
| curve 1 | 75,00 | 136,93 | $\mathbf{7 4 , 8 3}$ | $\mathbf{3 , 7 4}$ |
| curve 2 | 75,00 | 154,92 | $\mathbf{7 4 , 9 0}$ | $\mathbf{2 , 9 3}$ |
| curve 3 | 76,00 | 169,94 | $\mathbf{7 5 , 9 2}$ | $\mathbf{2 , 5 3}$ |
| curve 4 | 60,00 | 109,55 | $\mathbf{5 9 , 8 7}$ | $\mathbf{3 , 0 0}$ |

d) coordinates of the center of horizontal curve

$$
X_{s}=X-(R \cdot \sin \tau)[m]
$$

$$
Y_{s}=Y+(R \cdot \cos \tau)[m], \text { where: }
$$

$\mathrm{X}_{\mathrm{S}}$ - coordinates of the center of reduced horizontal curve $[\mathrm{m}]$
$\mathrm{Y}_{\mathrm{S}^{-}}$coordinates of the center of reduced horizontal curve [m]
$\tau$ - deflection angle of tangent on the end of the transition curve [rad]
$X_{s}=74,83-(250 \cdot \sin 0,150000)=37,47 m \quad Y_{s}=3,74+(250 \cdot \cos 0,150000)=250,94 m$

|  | $\mathbf{R}[\mathrm{m}]$ | $\mathbf{X}[\mathrm{m}]$ | $\mathbf{Y}[\mathrm{m}]$ | $\tau[\mathrm{rad}]$ | $\mathbf{X}_{\mathbf{s}}[\mathrm{m}]$ | $\mathbf{Y}_{\mathbf{s}}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| curve 1 | 250 | 74,83 | 3,74 | 0,150000 | $\mathbf{3 7 , 4 7}$ | $\mathbf{2 5 0 , 9 4}$ |
| curve 2 | 320 | 74,90 | 2,93 | 0,117188 | $\mathbf{3 7 , 4 8}$ | $\mathbf{3 2 0 , 7 3}$ |
| curve 3 | 380 | 75,92 | 2,53 | 0,100000 | $\mathbf{3 7 , 9 9}$ | $\mathbf{3 8 0 , 6 3}$ |
| curve 4 | 200 | 59,87 | 3,00 | 0,150000 | $\mathbf{2 9 , 9 8}$ | $\mathbf{2 0 0 , 7 5}$ |

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e) retraction of the horizontal curve
$H=Y-R \cdot(1-\cos \tau)[m]$
$H_{\text {min }}=0,5 m \leq H \leq H_{\text {max }}=2,5 m$, where:
H - retraction of the horizontal curve $[\mathrm{m}]$
$\tau$ - deflection angle of the tangent on the end of the horizontal curve [rad]
$H=Y-R \cdot(1-\cos \tau)=3,74-250 \cdot(1-\cos 0,150000)=0,94 m$

|  | $\mathbf{R}[\mathrm{m}]$ | $\mathbf{Y}[\mathrm{m}]$ | $\tau[\mathrm{rad}]$ | $\mathbf{H}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: | :---: |
| curve 1 | 250 | 3,74 | 0,150000 | $\mathbf{0 , 9 4}$ |
| curve 2 | 320 | 2,93 | 0,117188 | $\mathbf{0 , 7 3}$ |
| curve 3 | 380 | 2,53 | 0,100000 | $\mathbf{0 , 6 3}$ |
| curve 4 | 200 | 3,00 | 0,150000 | $\mathbf{0 , 7 5}$ |

For all transition curve the condition $\quad H_{\min }=0,5 m \leq H \leq H_{\max }=2,5 m \quad$ is fulfilled

## f) external

$N=\frac{Y}{\cos \tau} \quad[\mathrm{~m}]$, where:
N - external of the transition curve [m]
$\tau$ - deflection angle of the tangent on the end of the horizontal curve [rad]

$$
N=\frac{3,74}{\cos 0,150000}=3,79 \mathrm{~m}
$$

|  | $\mathbf{Y}[\mathrm{m}]$ | $\tau[\mathrm{rad}]$ | $\mathbf{N}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: |
| curve 1 | 3,74 | 0,150000 | $\mathbf{3 , 7 9}$ |
| curve 2 | 2,93 | 0,117188 | $\mathbf{2 , 9 5}$ |
| curve 3 | 2,53 | 0,100000 | $\mathbf{2 , 5 4}$ |
| curve 4 | 3,00 | 0,150000 | $\mathbf{3 , 0 3}$ |

g) short tangent
$T_{K}=\frac{Y}{\sin \tau} \quad[\mathrm{~m}]$, where:
$\mathrm{T}_{\mathrm{K}}$ - short tangent $[\mathrm{m}]$
$\tau$ - deflection angle of the tangent on the end of the horizontal curve [rad]
$T_{K}=\frac{3,74}{\sin 0,150000}=25,05 \mathrm{~m}$

|  | $\mathbf{Y}[\mathrm{m}]$ | $\tau[\mathrm{rad}]$ | $\mathbf{T}_{\mathbf{K}}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: |
| curve 1 | 3,74 | 0,150000 | $\mathbf{2 5 , 0 5}$ |
| curve 2 | 2,93 | 0,117188 | $\mathbf{2 5 , 0 3}$ |
| curve 3 | 2,53 | 0,100000 | $\mathbf{2 5 , 3 6}$ |
| curve 4 | 3,00 | 0,150000 | $\mathbf{2 0 , 0 4}$ |

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h) long tangent
$T_{D}=X-Y \cdot \operatorname{ctg} \tau \quad[\mathrm{~m}]$, where:
$\mathrm{T}_{\mathrm{D}}$ - long tangent [ m ]
$\tau$ - deflection angle of the tangent on the end of the horizontal curve [rad]
$T_{D}=74,83-3,74 \cdot \operatorname{ctg} 0,150000=50,06 \mathrm{~m}$

|  | $\mathbf{X}[\mathrm{m}]$ | $\mathbf{Y}[\mathrm{m}]$ | $\tau[\mathrm{rad}]$ | $\mathbf{T}_{\mathbf{D}}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: | :---: |
| curve 1 | 74,83 | 3,74 | 0,150000 | $\mathbf{5 0 , 0 6}$ |
| curve 2 | 74,90 | 2,93 | 0,117188 | $\mathbf{5 0 , 0 4}$ |
| curve 3 | 75,92 | 2,53 | 0,100000 | $\mathbf{5 0 , 6}$ |
| curve 4 | 59,87 | 3,00 | 0,150000 | $\mathbf{4 0 , 0 5}$ |

Uczelnia zintegrowana na przyszłość POWR.03.05.00-00-Z041/17

## i) $T_{s}$ section

$T_{S}=(R+H) \cdot \operatorname{tg} \frac{\gamma}{2}[\mathrm{~m}]$, where:
$\mathrm{T}_{\mathrm{S}}$ - length of the section $\mathrm{T}_{\mathrm{S}}[\mathrm{m}]$
$\gamma$ - deflection angle of the horizontal curve [rad]
$T_{S}=(250+0,94) \cdot \operatorname{tg} \frac{0,901167}{2}=121,40 \mathrm{~m}$

|  | $\mathbf{R}[\mathrm{m}]$ | $\mathbf{H}[\mathrm{m}]$ | $\gamma[\mathrm{rad}]$ | $\mathbf{T}_{\mathbf{s}}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: | :---: |
| curve 1 | 250 | 0,94 | 0,901167 | $\mathbf{1 2 1 , 4 0}$ |
| curve 2 | 320 | 0,73 | 0,706306 | $\mathbf{1 1 8 , 2 2}$ |
| curve 3 | 380 | 0,63 | 0,602422 | $\mathbf{1 1 8 , 2 5}$ |
| curve 4 | 200 | 0,75 | 0,851181 | $\mathbf{9 1 , 0 0}$ |

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## j) integer tangent

$T_{0}=X_{s}+T_{s} \quad[\mathrm{~m}]$, where:
$\mathrm{T}_{0}{ }^{-}$- integer tangent [m]
$\mathrm{T}_{0}=37,47+121,40=158,87 \mathrm{~m}$

|  | $\mathbf{X}_{\mathbf{s}}[\mathrm{m}]$ | $\mathbf{T}_{\mathbf{s}}[\mathrm{m}]$ | $\mathbf{T}_{\mathbf{0}}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: |
| curve 1 | 37,47 | 1211,40 | $\mathbf{1 5 8 , 8 7}$ |
| curve 2 | 37,48 | 118,22 | $\mathbf{1 5 5 , 7 1}$ |
| curve 3 | 37,99 | 118,25 | $\mathbf{1 5 6 , 2 4}$ |
| curve 4 | 29,98 | 91,00 | $\mathbf{1 2 0 , 9 8}$ |

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## k) central angle of the reduced horizontal curve

```
\alpha=\gamma-2\cdot\tau [m], where:
\gamma-deflection angle of the horizontal curve [rad]
\tau- deflection angle of the tangent on the end of the horizontal curve [rad]
\alpha-central angle of the reduced horizontal curve [rad]
\alpha=0,901167-2\cdot0,150000 = 0,601167 rad
```

|  | $\gamma[\mathrm{rad}]$ | $\tau[\mathrm{rad}]$ | $\alpha[\mathrm{rad}]$ | $\alpha\left[^{\circ}\right]$ |  |
| :---: | :---: | :---: | :---: | :--- | :---: |
| curve 1 | 0,901167 | 0,150000 | 0,601167 | $34^{\circ} 26^{\prime} 40^{\prime \prime}$ | $\mathbf{3 4 , 4 4 4 3}$ |
| curve 2 | 0,706306 | 0,117188 | 0,471931 | $27^{\circ} 02^{\prime} 23^{\prime \prime}$ | $\mathbf{2 7 , 0 3 9 7}$ |
| curve 3 | 0,602422 | 0,100000 | 0,402422 | $23^{\circ} 03^{\prime} 26^{\prime \prime}$ | $\mathbf{2 3 , 0 5 7 1}$ |
| curve 4 | 0,851181 | 0,150000 | 0,551181 | $31^{\circ} 34^{\prime} 49^{\prime \prime}$ | $\mathbf{3 1 , 5 8 0 3}$ |

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## I) length of the reduced horizontal curve

$\mathrm{E}=\mathrm{R} \cdot \mathrm{a}$ [m], where:
$\alpha$ - central angle of the reduced horizontal curve [rad]
Ł- length of the reduced horizontal curve [m]
$Ł=250 \cdot 0,601167=150,29 \mathrm{~m}$

|  | R $[\mathrm{m}]$ | $\alpha[\mathrm{rad}]$ | $\mathbf{L}[\mathrm{m}]$ |
| :---: | :---: | :---: | :---: |
| curve 1 | 250 | 0,601167 | $\mathbf{1 5 0 , 2 9}$ |
| curve 2 | 320 | 0,471931 | $\mathbf{1 5 1 , 0 2}$ |
| curve 3 | 380 | 0,402422 | $\mathbf{1 5 2 , 9 2}$ |
| curve 4 | 200 | 0,551181 | $\mathbf{1 1 0 , 2 4}$ |

## Coordinates for staking out the transition curve

Intermediate points for the transition curves in local coordinate systems

$$
x(l)=l-\frac{l^{5}}{40 a^{4}}+\frac{l^{9}}{3456 a^{8}}-(\ldots)[m] \quad y(l)=\frac{l^{3}}{6 a^{2}}-\frac{l^{7}}{336 a^{6}}+\frac{l^{11}}{42240 a^{10}}-(\ldots)[m], \text { where: }
$$

$x(1)$ - local coordinate of the intermediate point of the transition curve [m]
$y(1)$ - local coordinate of the intermediate point of the transition curve [m]
where: $0 \leq 1 \leq \mathrm{L}$

$$
x(l)=50,00-\frac{50,00^{5}}{40 \cdot 136,93^{4}}+(\ldots)=49,98 m \quad y(l)=\frac{50,00^{3}}{6 \cdot 136,93^{2}}-\frac{50,00^{7}}{336 \cdot 136,93^{6}}+(\ldots)=1,11 m
$$

Transformation of the coordinate from the local system to the global system

$$
\left\{\begin{array}{l}
X=x \cdot \cos \alpha-y \cdot \sin \alpha+a \\
Y=x \cdot \sin \alpha+y \cdot \cos \alpha+b
\end{array}\right.
$$

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## Mileage of the horizontal alignment



[^0]Signs:
PA - PPT - BDR - begin of the design road
W-V-vertex point
PŁK - BC - begin of the curve
$K Ł K-E C$ - end of the curve
PKP - BTC - begin of the transition curve
KKP - ETC - end of the transition curve
ŚŁK - CC - center of the curve
PB - KPT - EDR - end of the design road
L - the length of the clothoid
$Ł-L^{\prime}$ - the length of the reducted curve
$\mathrm{T}_{\mathrm{o}}$ - the length of the integer tangent

| $+\mathrm{L}_{3}$ | + | 76,00 |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $\underline{-T_{03}}$ |  | $\begin{array}{r} \hline 1+920,67 \\ 156,24 \\ \hline \end{array}$ | $\overline{\mathrm{PKP}_{3}}$ |  |
| $+\mathrm{W}_{3} \mathrm{~W}_{4}$ | + | $\begin{array}{r} \hline 1+764,43 \\ 943,65 \\ \hline \end{array}$ | $\mathrm{W}_{3}{ }^{*}$ |  |
| $\underline{-\mathrm{T}_{04}}$ | - | $\begin{array}{r} \hline 2+708,08 \\ 120,98 \\ \hline \end{array}$ | $\mathrm{W}_{4}$ |  |
| $+\mathrm{L}_{4}$ | $+$ | $\begin{array}{r} \hline 2+587,10 \\ 60,00 \\ \hline \end{array}$ | $\mathrm{PKP}_{4}$ |  |
| $\underline{+\mathrm{E}_{4} / 2}$ | $+$ | $\begin{array}{r} 2+647,10 \\ 55,12 \\ \hline \end{array}$ | $\mathrm{KKP}_{4}=\mathrm{PEK}_{4}$ | $\begin{aligned} \mathrm{W}_{4}-\mathrm{W}_{4} * & =2 \cdot \mathrm{~T}_{\sigma}-2 \cdot \mathrm{~L}-\mathrm{L} \\ 2708,08-2696,36 & =2 \cdot 120,98-2 \cdot 60,000-110,24 \end{aligned}$ |
| + $\mathrm{E}_{4} / 2$ |  | $\begin{array}{r} \hline 2+702,22 \\ 55,12 \\ \hline \end{array}$ | ŚŁK4 | $11,72=11,72$ |
| $\underline{+}$ | $+$ | $\begin{array}{r} 2+757,34 \\ 60,00 \\ \hline \end{array}$ | $\mathrm{K} \mathrm{K}_{4}=\mathrm{KKP}_{4}$ |  |
| $\underline{-T_{04}}$ |  | $\begin{array}{r} 2+817,34 \\ 120,98 \\ \hline \end{array}$ | $\overline{\mathrm{PKP}_{4}}$ |  |
| $+\mathrm{W}_{4} \mathrm{~B}$ | $+$ | $\begin{array}{r} \hline 2+696,36 \\ 285,94 \\ \hline \end{array}$ | $\mathrm{W}_{4}{ }^{*}$ |  |
|  |  | 2+982,30 | B |  |

Verification:
$\mathrm{AW}_{1}-\left(\mathrm{W}_{1}-\mathrm{W}_{1}{ }^{*}\right)+\mathrm{W}_{1} \mathrm{~W}_{2}-\left(\mathrm{W}_{2}-\mathrm{W}_{2}{ }^{*}\right)+\mathrm{W}_{2} \mathrm{~W}_{3}-\left(\mathrm{W}_{3}-\mathrm{W}_{3}{ }^{*}\right)+\mathrm{W}_{3} \mathrm{~W}_{4}-\left(\mathrm{W}_{4}-\mathrm{W}_{4}{ }^{*}\right)+\mathrm{W}_{4} \mathrm{~B}=\mathrm{KT}$
$619,90-(619,90-602,45)+454,56-(1057,01-1046,62)+725,36$
$-(1771,98-1764,43)+943,65-(2708,08-2696,36)+285,94=2982,30$
$2982,30=2982,30$

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## Literature:

http://onlinemanuals.txdot.gov/txdotmanuals/rdw/horizontal alignment.htm
https://engineering.purdue.edu/~ce361/JFRICKER/HW/HC 02fHW6.pdf

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## THANK YOU FOR YOUR ATTENTION

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